

SMT363XC2

User Manual



Revision History

Date	Comments	Engineer	Version
14/11/03	First release	JPA	1.0.0
02/12/03	Added addressing mode section (LED Setting) Updated ComPort section	JPA	1.0.1
20/10/04	Updated block diagram. Removed endianess section Updated LED section Replaced Timer and interrupt section by Interrupt section	JPA	1.0.2
07/06/05	Added: power consumption	SM	1.0.3
09/08/05	Update: Support the firmware V1.1	SM	2.0
05/12/05	Updated LED descriptions.	GP	2.1
29/11/07	Removed HPI connection from block diagram.	GP	2.2

Table of Contents

Revision History.....	2
Table of Contents	3
Contacting Sundance	5
Notational Conventions	6
DSP	6
SDB	6
SHB	6
Register Descriptions.....	6
Outline Description	7
Intended Audience.....	7
Block Diagram	8
Architecture Description	9
NET+50	9
DSP	9
Boot Mode.....	9
DPRAM.....	10
EMIF Control Registers.....	10
CE1 - IO Control	11
SDRAM.....	11
FLASH.....	11
RS232	12
Serial ports	12
FPGA.....	12
Version control	12
Firmware versions	12
Reprogramming the firmware and boot code.....	12
Comports	13
SHB	13
Architecture.....	13
Global bus	13

LED Setting	14
LED Register.....	14
CONFIG & NMI.....	15
Config Register	15
Timer	16
Timer Control Register.....	16
IIOF interrupt	17
Code Composer	18
Application Development.....	18
SMT6400	18
SMT6060	18
3L Diamond.....	18
SMT6500	18
FPGA Memory Map.....	19
SHB pinout	20
SHB generic pin-out.....	20
Jumper Pin-Outs.....	21
JP1 - NET+50 connections	21
JP2 - Serial port header.....	21
JP3 - Xilinx CPLD programming port	22
JP4 - NetICE port.....	22
LED Descriptions	23
Mechanical Configuration	24
Operating Conditions	25
Safety	25
EMC	25
General Requirements	25
Power Consumption.....	25
Bibliography	26
INDEX	27

Contacting Sundance

You can contact Sundance for additional information by login onto the [Sundance support forum](#). Please note that first users have to [register first](#).

Notational Conventions

DSP

The terms DSP, C6713 and TMS320C6713 will be used interchangeably throughout this document.

SDB

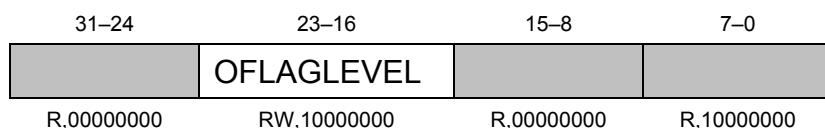
The term SDB will be used throughout this document to refer to the Sundance Digital Bus interface.

SHB

The term SHB will be used throughout this document to refer to the Sundance High-speed Bus interface.

Register Descriptions

The format of registers is described using diagrams of the following form:



The digits at the top of the diagram indicate bit positions within the register and the central section names bits or bit fields. The bottom row describes what may be done to the field and its value after reset. Shaded fields are reserved and should only ever be written with zeroes.

R Readable by the CPU

W Writeable by the CPU

RW Readable and writeable by the CPU

Binary digits indicate the value of the field after reset

Outline Description

The SMT363XC2 is an Ethernet module, size 1 TIM offering the following features:

- ❑ NetSilicon ARM-chip Net+50
- ❑ TMS320C6713 processor running at 225MHz
- ❑ Six Comports
- ❑ 64MB of SDRAM
- ❑ 8MB Flash ROM
- ❑ Global Bus connector
- ❑ High bandwidth data I/O via 2 Sundance Digital Buses (SDB)

Intended Audience

There are two existing versions of the firmware for the SMT363XC2. These two versions differ by the number and the type of communication resources (comport and SDB interfaces) provided.

For each of the versions of the different firmware is loaded in the FPGA:

- Firmware version 1.0 or
- Firmware version 1.1

This user manual covers the version 1.1 of the firmware for the SMT363XC2 implemented with the model described in the [SMT6500 help file](#).

The changes between the firmware version 1.0 and version 1.1 are described in the section [Firmware versions](#).

Block Diagram

The following drawing shows the block diagram of the SMT363XC2 module.

The main components of the SMT363XC2 are:

- A Texas Instruments DSP
- One Xilinx Virtex-II FPGA
- One NetSilicon ARM Net+50 device with integrated MAC controller for connection to an Ethernet network.
- 16/64MB of SDRAM

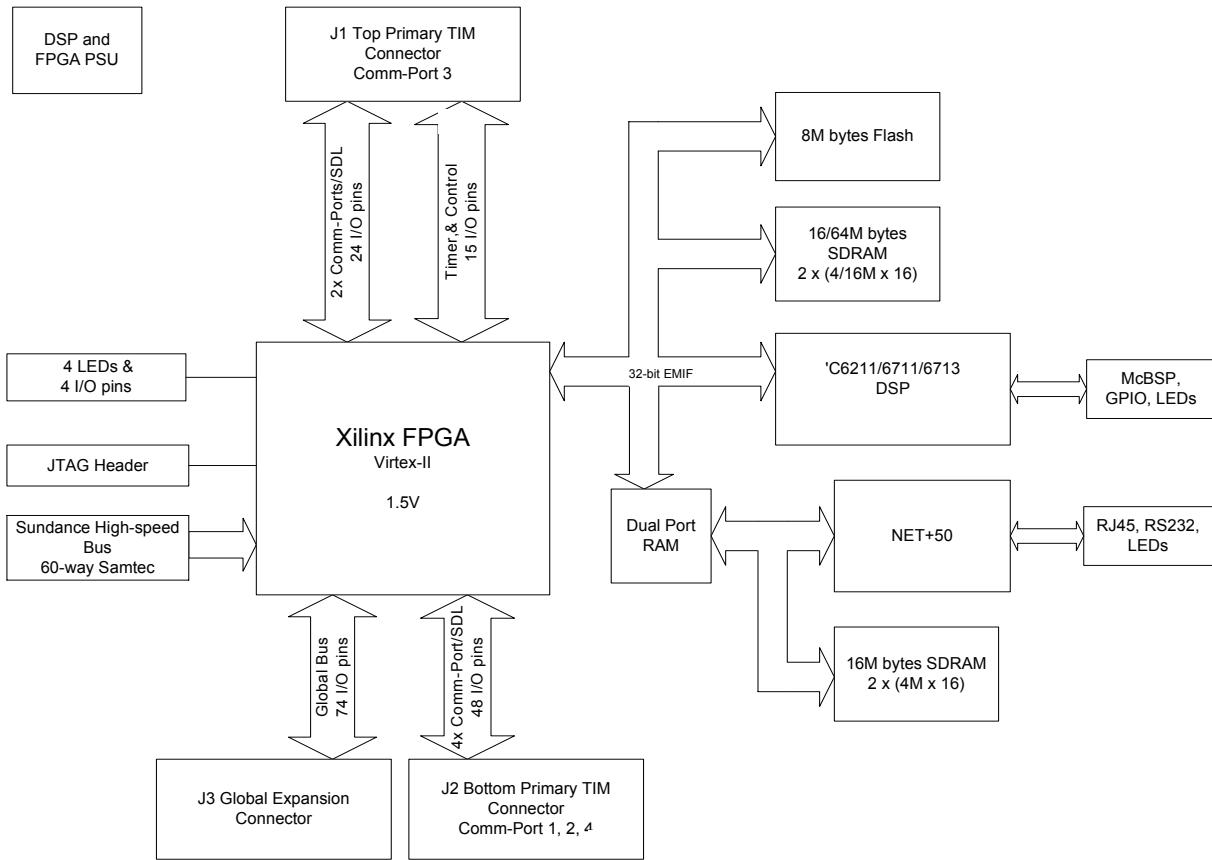


Figure 1: SMT363XC2 block diagram

Architecture Description

NET+50

The NET+50 is a cost-effective, high-performance 32-bit network attached microprocessor developed especially for high-bandwidth applications in Intelligent Networked Devices. Based on ARM's architecture, it integrates 10/100Base-T Ethernet MAC with an MII interface, a distributed 10-channel linking DMA controller and a memory controller supporting all of the popular memory devices in use today.

This device is connected directly to an Intel LXT971 PHY device, which provides an IEEE 802.3 compatible 10Base-T and 100Base-T physical layer interface.

Also, directly connected to the NET+50 are 16Mbytes of SDRAM, an RS232 level converter and a 128KB Dual Port RAM (DPRAM).

LEDs 4 and 4 are controlled via PORTA bits 0 and 1.

DSP

The Texas Instruments DSP can run at up to 225MHz. The DSP is doted of 16MB (*optional 64MB*) of SDRAM.

The DSP is a **TMS320C6713** type.

An on-board 37.5MHz crystal oscillator provides the clock used for the DSP which then multiplies this by for input to the DSP. DSP internally multiplies this up to the required frequency, using a PLL.

Boot Mode

The DSP is connected to the on-board flash ROM that contains the Sundance bootloader and the FPGA bitstream.

Following reset, the DSP will automatically load the data from the flash ROM into its internal program memory at address 0 and then start executing from there. All this code is the Sundance *bootloader*, and it is made up of three parts: FPGA configuration, processor configuration and the *Comport boot procedure*. FPGA configuration uses data in the ROM to configure the FPGA. A processor configuration sets the processor into a standard state, copies its comport boot procedure into a dual-port RAM (DPRAM) implemented in the FPGA, and releases the NET+50 chip from reset. The Net+50 chip is configured to boot from this DPRAM.

The bootloader is executed. It will continually check the six comports until data appears on one of them. This will next load a program in boot format from this comport. Note that the bootloader will not read data arriving on other comports. Finally the control is passed to the loaded DSP application.

It is safest to wait for the configuration to complete. Note that comports will appear to be "not ready" until the FPGA has been configured.

The FPGA programming algorithm is not described here. It can be found in the boot code.

DPRAM

The DPRAM in the FPGA is only intended to be used during this boot process; more general use is not recommended.

A 128KB memory is directly connected to both the DSP and the NET+50 devices. Each can access the memory independently and at their respective maximum data rates.

The DPRAM is decoded as the boot ROM in the NET+50's memory space.

The DPRAM supports the generation of interrupts to either of its ports. This functionality is achieved by the DSP writing to a specific DPRAM address, which in turn generates an interrupt to the NET+50 (PINT2* pin). Similarly, the NET+50 can write to a specific address which generates an interrupt which can be routed to the DSP.

EMIF Control Registers

The DSP has a single external memory interface (EMIF) which is 32 bits wide.

A full description of the registers used to control the EMIF can be found in the [DSP C6000 Peripherals Reference Guide](#)
Error! Reference source not found.
Error! Reference source not found..

The standard bootstrap will initialise these registers to use the following resources:

Memory space (EMIF)	Resource	Address range
CE0	SDRAM	0x80000000 - 0x83FFFFFF
CE1	Flash / IO Control	0x90000000 - 0x903FFFFFF
CE2	DPRAM	0xA0000000 - 0xA7FFFFFF
CE3	Virtex	0xB0000000 - 0xB0FFFFFF

The power on (and reset) state for the semaphore enable (DPRAM related) is disabled. This bit determines whether the flash or DPRAM-semaphore registers are accessed on CE1.

CE1 - IO Control

Several I/O connections are required to control the NET+50 reset signal, upper flash address signals, and the control signals for FPGA programming. These are all accessed via the CE1 memory space and defined settings for some data lines.

D31	D30	D29	D0	Function
0	0	0	X	Flash write
0	0	1	N	NET+50 reset control. Reset(active low)=N
0	1	0	N	Flash address A20 control. A20=N
0	1	1	N	Flash address A21 control. A21=N
1	0	0	N	FPGA PROG pin control. PROG(active low)=N
1	0	1	X	FPGA CCLK pin control. Generates pulse on CCLK
1	1	0	N	DPRAM semaphore enable when N=1

SDRAM

Memory space CE0 is used to access 16MB (or optional 64MB) of SDRAM over the EMIF.

The speed of the SDRAM is dependent on the processor variant. Using the C6713, the SDRAM will operate at 100MHz.

Using the C6713, the SDRAM operates at a programmable rate up to the maximum allowed on the EMIF.

The EMIF CE0 memory space control register should be programmed with the value 0x00000030.

FLASH

An 8MB Flash ROM is connected to the DSP in the EMIF CE1 memory space. The ROM holds boot code for the DSP, configuration data for the FPGA, the boot code for the Net+50 chip and optional user-defined code.

A software protection algorithm is in place to prevent programs accidentally altering the ROM's contents. Please [contact Sundance](#) for further information about re-programming this device.

The CE1 memory space control register should be programmed with the value 0xFFFFFFF23.

RS232

A single RS-232 channel is provided at true RS232 levels. The signals provided are TBD and are presented on wire-wrap posts.

Serial ports

The DSP provides two serial ports, which are connected to a pin header on the SMT363XC2 module. Additionally, some of the serial port signals are connected to the Virtex2 FPGA in order to provide extra signals, which can be used for external interrupts.

FPGA

The FPGA (Field Programmable Gate Array) is a Xilinx Virtex-II XC2V1000 device.

It implements the following communication resources:

- Six comport interfaces
- Two 16-bit Sundance Digital Bus interfaces
- One global bus interface

Version control

Revision numbers for both the boot code and FPGA firmware are stored in the Flash ROM during programming as zero-terminated ASCII strings.

The [SMT6001 utility](#) can be used to display the version numbers of the bootloader and the FPGA data.

Firmware versions

The SMT6001 utility includes the latest version of the bootloader and the latest version of the FPGA data that implements the FPGA architecture described in the [SMT6500 help file](#).

Note that the new firmware supports two more comports. Customers who wish to use the old firmware that supported only 4 comports options can obtain it [from our support web forum](#).

Reprogramming the firmware and boot code

The contents of the flash ROM are managed using the [SMT6001 utility](#). This includes the latest firmware and bootloader along with complete documentation on how to reprogram the ROM. The utility assumes that you have Code Composer Studio installed and that it has been configured correctly for the installed TIMs. The Sundance Wizard can help you with this.

To confirm that the ROM has been programmed correctly, you should run the confidence test in the BoardInfo utility (SMT6300).

Comports

The DSP has 6 comports, numbered 0 to 5.

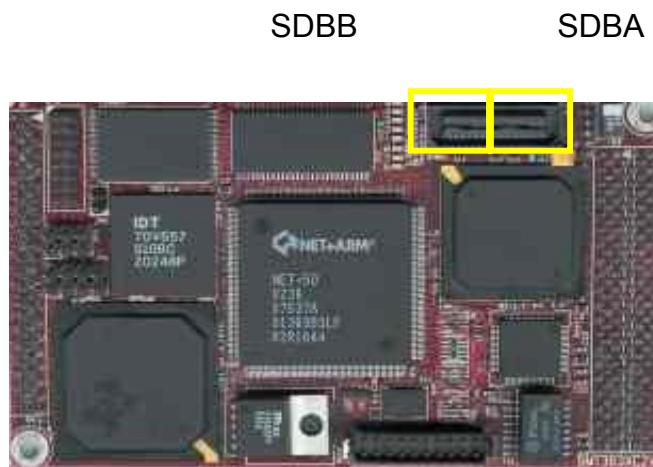
The addresses of the Comport registers are shown in the [Error! Reference source not found.](#), and are described in the [SMT6400 help file](#).

SHB

The SMT363XC2 provides one SHB connector, which is connected to the DSP to give two 16-bit SDB interfaces. These interfaces operate with a fixed clock rate of 100MHz.

Architecture

SDB0 and SDB1 on the DSP are presented on the TIM's SHB connector, SDBA and SDBB respectively.



The addresses of the SDB registers are shown in the [Virtex Memory Map](#), and are described in the [SMT6400 help file](#).

Global bus

The SMT363XC2 provides a single global bus interface. This is only accessible from the DSP. The addresses of the global bus registers are shown in the [Virtex Memory Map](#), and are described in the [SMT6400 help file](#).

LED Setting

The SMT363XC2 has 8 LEDs.

LED D1 always displays the state of the FPGA DONE pin. This LED is off when the FPGA is configured (DONE=1) and on when it is not configured (DONE=0).

This LED should go on when the board is first powered up and go off when the FPGA has been successfully programmed (this is the standard operation of the boot code resident in the flash memory device). If the LED does not light at power-on, check that you have the mounting pillars and screws fitted properly. If it stays on, the DSP is not booting correctly, or is set to boot in a non-standard way.

Two of the LEDs (D2-3) can be controlled with the LED register. Writing 1 will illuminate the LED; writing 0 will turn it off.

LED Register

(0xB00D0000)

31–4	3	2	1	0
RW,0	-	-	LED D3	LED D2

Despite LED register bit 2 is writable; user should not change the value of this bit.

When SMT363XC2 embeds 16MB of SDRAM, the DSP is configured to access SDRAM with 8 column address bits and 12 row address bits, whereas when SMT363XC2 embeds 64MB SDRAM, it's configured with 10 column address bits and 13 row address bits (EMIF SDRAM Control register).

It results that FPGA's is moved in the DSP's memory space.

Writing a value to this bit changes the way the FPGA decodes the address, and therefore it's location in the EMIF memory space.

This bit should be set to '1' when 64MB of SDRAM are fitted on-board; otherwise it should be set to '0' when 16MB of SDRAM are fitted on-board.

CONFIG & NMI

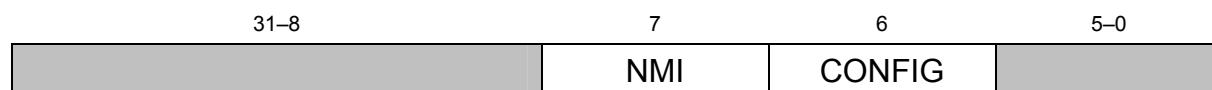
The TIM specification describes the operation of an open-collector type signal CONFIG that is driven low after reset.

This signal, on a standard C4x based TIM, is connected to the processor's IIOF3 pin. On the SMT365, the CONFIG signal is asserted after power on, and can be released by writing the value (1<<6) to the config register. Conversely, CONFIG may be re-asserted by writing 0 to this bit. It is not possible for software to read the state of the CONFIG signal.

The NMI signal from the TIM connector can be routed to the DSP NMI pin.

WARNING: Several software components include code sequences that assume setting GIE=0 in the DSP CSR will inhibit all interrupts; NMI violates that assumption. If an NMI occurs during such code sequences it may not be safe to return from the interrupt. This may be particularly significant if you are using the compiler's software pipelining facility.

Config Register



Field	Description
CONFIG	0 drive CONFIG low 1 tri-state CONFIG
NMI	0 Disconnect NMI from the DSP 1 Connect NMI from TIM to the DSP.

Config and NMI DSP lines are described in the [SMT6400 help file](#).

Timer

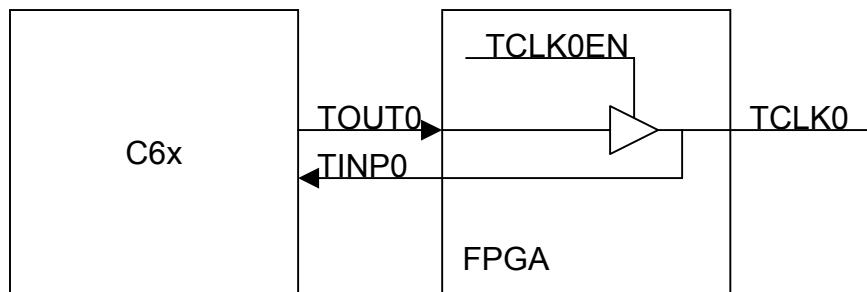
The TIM TCLK0 and TCLK1 signals can be routed to the DSP's TOUT/TINP pins. The signal direction must be specified, together with the routing information in the timer control register.

Timer Control Register

31–6	5	4	3–0
Reserved	TCLK1	TCLK0	Reserved

Field	Description
TCLK0	0 TIM TCLK0 is an input 1 Enable TIM TCLK0 as an output
TCLK1	0 TIM TCLK1 is an input 1 Enable TIM TCLK1 as an output

If the TIM TCLKx pin is selected as an output, the DSP TOUTx signal will be used to drive it. The TIM TCLKx pin will always drive the DSP TINPx input.



The Timer control register is described in the [SMT6400 help file](#).

IIOF interrupt

The firmware can generate pulses on the external interrupt lines of the TIM.

Only the interrupt line IIOF1 and IIOF2 are connected from/to the DSP and the HOST.

- IIOF1 is connected from the DSP side to the HOST side: so, the DSP interrupts the HOST
- IIOF2 is connected from the HOST side to the DSP side: so, the HOST interrupts the DSP

The IIOF interrupt lines are described in the [SMT6400 help file](#).

Code Composer

This module is fully compatible with the Code Composer Studio debug and development environment. This extends to both the software and JTAG debugging hardware. The driver to use is the *tixds6x1x_11.dvr*. CCS version 3.0 or later is required as the reprogramming utility (SMT6001) requires it.

- Troubleshooting

Our [Knowledge data base](#) and [FAQ](#) sections may help you to resolve some known issues.

Application Development

Depending on the complexity of your application, you can develop code for SMT363XC2 modules in several ways.

SMT6400

For simple applications, the Sundance [SMT6400 software support package](#) (project examples) and its associated header files (SmtTim.h and ModSup.h) can suffice.

The SMT6400 product is installed by the Sundance Wizard and it is free of charge.

SMT6060

[SMT6060-FTP](#) is a utility that allows and easy and cost-effective integration of the [Net+50 ARM](#) chip and the DSP that can be found on SMT363. It is ready to use and provide a [TCI/IP interface to a host](#).

[SMT6060-TCP/IP](#) is a software package that provides Ethernet connectivity via the industry standard Berkeley sockets interface to a 3L/Diamond network of DSP processors. The package is typically used when there is at least one SMT363 present in the system; however, using a feature of the SMT6025 software package, it also provides seamless connectivity via the HOST PC's (Winsock 2.2) Ethernet hardware. The software is ready-to-use and provides sockets connectivity to any Sundance DSP processor.

3L Diamond

This module is fully supported by 3L Diamond, which Sundance recommends for all but the simplest of applications. An SMT363XC2 has to be declared as appropriate in configuration files as one processors of type:

- **SMT363XC2_1** (16MB SDRAM)
- **SMT363XC2_2** (64MB SDRAM)

SMT6500

This is the [support package for the FPGA](#). It may be used to develop your application in the FPGA of the module.

FPGA Memory Map

```
volatile unsigned *SMT363CP0          = (unsigned *) 0xB0000000;  
volatile unsigned *SMT363CP1          = (unsigned *) 0xB0008000;  
volatile unsigned *SMT363CP2          = (unsigned *) 0xB0010000;  
volatile unsigned *SMT363CP3          = (unsigned *) 0xB0018000;  
volatile unsigned *SMT363CP4          = (unsigned *) 0xB0020000;  
volatile unsigned *SMT363CP5          = (unsigned *) 0xB0028000;  
volatile unsigned *SMT363CP0_STAT    = (unsigned *) 0xB0004000;  
volatile unsigned *SMT363CP1_STAT    = (unsigned *) 0xB000C000;  
volatile unsigned *SMT363CP2_STAT    = (unsigned *) 0xB0014000;  
volatile unsigned *SMT363CP3_STAT    = (unsigned *) 0xB001C000;  
volatile unsigned *SMT363CP4_STAT    = (unsigned *) 0xB0024000;  
volatile unsigned *SMT363CP5_STAT    = (unsigned *) 0xB002C000;  
volatile unsigned *SMT363STAT        = (unsigned *) 0xB003C000;  
volatile unsigned *SMT363SDBA        = (unsigned *) 0xB0040000;  
volatile unsigned *SMT363SDBB        = (unsigned *) 0xB0050000;  
volatile unsigned *SMT363SDBA_STAT  = (unsigned *) 0xB0048000;  
volatile unsigned *SMT363SDBB_STAT  = (unsigned *) 0xB0058000;  
volatile unsigned *SMT363SDBA_FLAG  = (unsigned *) 0xB004C000;  
volatile unsigned *SMT363SDBB_FLAG  = (unsigned *) 0xB005C000;  
volatile unsigned *GLOBAL_BUS        = (unsigned *) 0xB00A0000;  
volatile unsigned *GLOBAL_BUS_CTRL   = (unsigned *) 0xB0080000;  
volatile unsigned *GLOBAL_BUS_START  = (unsigned *) 0xB0088000;  
volatile unsigned *GLOBAL_BUS_LENGTH = (unsigned *) 0xB0090000;  
volatile unsigned *SMT363TCLK        = (unsigned *) 0xB00C0000;  
volatile unsigned *SMT363TIMCONFIG   = (unsigned *) 0xB00C8000;  
volatile unsigned *SMT363LED         = (unsigned *) 0xB00D0000;  
volatile unsigned *SMT363INTCTRL4    = (unsigned *) 0xB00E0000;  
volatile unsigned *SMT363INTCTRL4_EXT = (unsigned *) 0xB00E4000;  
volatile unsigned *SMT363INTCTRL5    = (unsigned *) 0xB00E8000;  
volatile unsigned *SMT363INTCTRL4_EXT = (unsigned *) 0xB00Ec000;  
volatile unsigned *SMT363INTCTRL6    = (unsigned *) 0xB00F0000;  
volatile unsigned *SMT363INTCTRL4_EXT = (unsigned *) 0xB00f4000;  
volatile unsigned *SMT363INTCTRL7    = (unsigned *) 0xB00F8000;  
volatile unsigned *SMT363INTCTRL4_EXT = (unsigned *) 0xB00fc000;
```

SHB pinout

SHB generic pin-out

Hw	QSH Pin number	QSH Pin number	Hw
Hw0	CLK	1	2
	D1	3	4
	D3	5	6
	D5	7	8
	D7	9	10
	D9	11	12
	D11	13	14
	D13	15	16
	D15	17	18
	USERDEF1	19	20
	USERDEF3	21	22
	REQ	23	24
		25	26
		27	28
		29	30
		31	32
		33	34
		35	36
Hw1	CLK	37	38
	D1	39	40
	D3	41	42
	D5	43	44
	D7	45	46
	D9	47	48
	D11	49	50
	D13	51	52
	D15	53	54
	USERDEF1	55	56
	USERDEF3	57	58
	REQ	59	60

Note: Hw is a short for Half-word (i.e. 16-bit Word)

Jumper Pin-Outs

JP1 - NET+50 connections

1 SPI_CLK	11 SPE_EN
2 SPI_RX	12 SPI_TX
3 RXD	13 TXD
4 RTS	14 CTS
5 DTR	15 DCD
6 DSR	16 RI
7 V33	17 GND
8 FA6	18 FA78
9 FA3	19 FA45
10 FA1	20 FA2

JP2 - Serial port header

2	4	6	8	10	12	14	16
FSX1	FSR1	DX1	DR1	CLKX1	CLKR1	CLKS1	GND
FSX2	FSR2	DX2	DR2	CLKX2	CLKR2	CLKS2	GND
1	3	5	7	9	11	13	15

Refer to the DSP's Peripheral Reference Guide for signal description and usage.

JP3 - Xilinx CPLD programming port.

1 V33	2 TCK
3 GND	4 TMS
5 TDO	6 TDI

JP4 - NetICE port

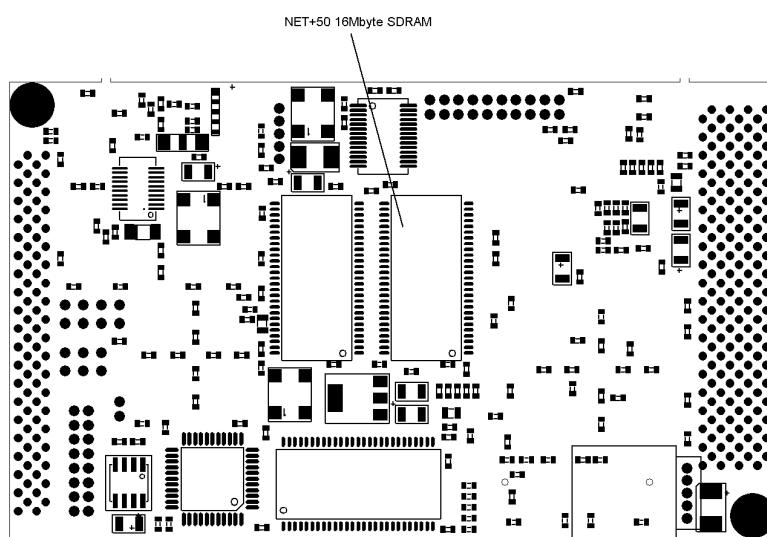
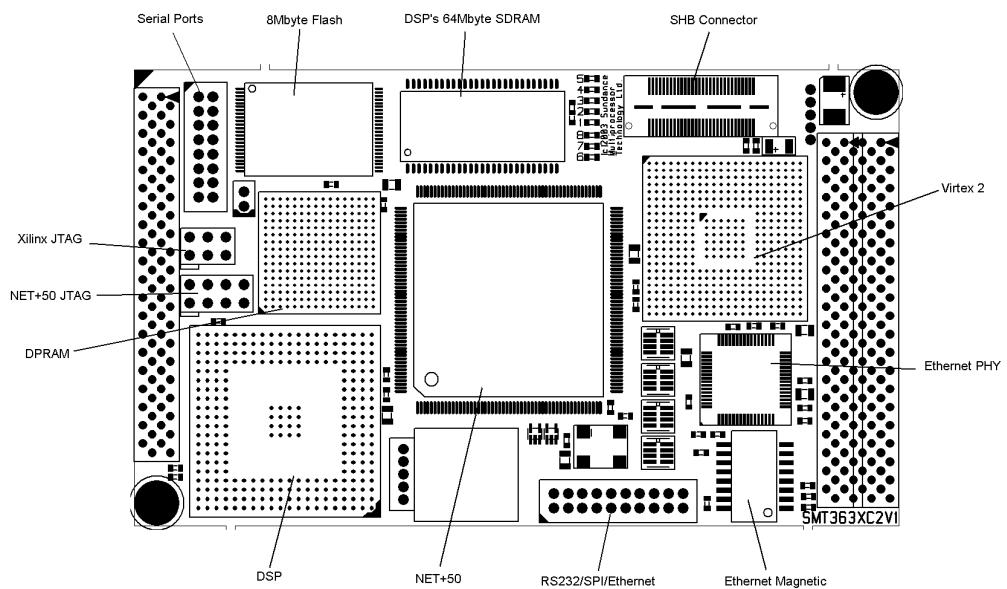
1 TCLK	2 TRST (NC)
3 TMS	4 NC
5 TDI	6 V33
7 TDO	8 GND

Typically, TRST is not connected to the NET+50.

LED Descriptions

LED	Connection	Function
1	FPGA.DONE	Shows the state of the FPGA's configuration. If this LED is ON, then the FPGA is NOT configured. This LED should power up in the ON state and extinguish after a second.
2	FPGA.LED0	Controlled by the LED register. DSP Heartbeat (SMT6060-TCPIP, rpcproxy.tsk)
3	FPGA.LED1	Controlled by the LED register.
4	NET50.PORTA0	Controlled by PORTA bit 0 of the NET+50. Net+50 Heartbeat (SMT6060-TCPIP, netsocksvr_v0p5p7.dat)
5	NET50.PORTA1	Controlled by PORTA bit 1 of the NET+50.
6	PHY.LED3	Link receive status (ON=receiving, OFF=not receiving)
7	PHY.LED2/NET50.PORTC6	Link up status (ON=connected, OFF=disconnected)
8	PHY.LED1	Link speed status (ON=100Mbit, OFF=10Mbit)

Mechanical Configuration



Operating Conditions

Safety

The module presents no hazard to the user.

EMC

The module is designed to operate within an enclosed host system that provides adequate EMC shielding. Operation within the EU EMC guidelines is only guaranteed when the module is installed within an appropriate host system.

The module is protected from damage by fast voltage transients introduced along output cables from outside the host system.

Short-circuiting any output to ground does not cause the host PC system to lock up or reboot.

General Requirements

The module must be fixed to a TIM40-compliant carrier board.

The SMT363XC2 TIM is in a range of modules that must be supplied with a 3.3V power source. In addition to the 5V supply specified in the TIM specification, these new generation modules require an additional 3.3V supply to be presented on the two diagonally-opposite TIM mounting holes. The lack of this 3.3V power supply should not damage the module, although it will obviously be inoperable; prolonged operation under these circumstances is not recommended.

The SMT363XC2 is compatible with all Sundance TIM carrier boards. It is a 5V tolerant module, and as such, it may be used in mixed systems with older TIM modules, carrier boards and I/O modules.

Use of the TIM on SMT327 (cPCI) motherboards may require a firmware upgrade. If LED D6 on the SMT363XC2 remains illuminated once the TIM is plugged in and powered up, the SMT327 needs the upgrade. The latest firmware is supplied with all new boards shipped. Please contact Sundance directly if you have an older board and need the upgrade.

The external ambient temperature must remain between 0 °C and 40 °C, and the relative humidity must not exceed 95% (non-condensing).

Power Consumption

The power consumption of this TIM is dependent on the operating conditions in terms of core activity and I/O activity. The SMT363XC2 module consumes about 3.18 Watts.

Bibliography

1. [Sundance Help file](#)
2. [SMT6400 help file](#) (DSP support package) and [SMT6500 help file](#) (FPGA support package)
3. [SMT6060 user manual](#) (Ethernet support package)
4. [NET+50 Microprocessor](#)
5. [TMS320C6000 Peripherals Reference Guide](#) (literature number SPRU190)
It describes common peripherals available on the TMS320C6000 digital signal processors. This book includes information on the internal data and program memories, the external memory interface (EMIF), the host port, multichannel-buffered serial ports, direct memory access (DMA), clocking and phase-locked loop (PLL), and the power-down modes.
6. [TIM-40 MODULE SPECIFICATION](#) Including TMS320C44 Addendum
7. [SDB Technical Specification](#)
8. [SHB Technical Specification](#)
9. [TMS320C4x User's Guide](#) (literature number SPRU063)
It describes the C4x 32-bit floating-point processor, developed for digital signal processing as well as parallel processing applications. Covered are its architecture, internal register structure, instruction set, pipeline, specifications, and operation of its six DMA channels and six communication ports. Software and hardware applications are included.
10. [Xilinx Virtex-II datasheet](#)
11. [TMSC6713 datasheet](#)



Certificate Number FM 55022

INDEX

A

Application Development · 18

B

Bibliography · 26

C

Code Composer · 18
CONFIG & NMI · 15
Contacting Sundance · 5

E

email address · 5

F

Firmware versions · 12

I

IIOF lines · 17

L

LEDs · 14
FPGA DONE pin · 14
LED register · 14

M

memory space (CE0 to CE3) · 10

N

Notational Conventions · 6

O

Operating Conditions · 25

P

Power consumption · 25

R

Register Descriptions · 6

S

SDB · 13
SHB pinout · 20
SMT6400 · 18
SMT6500 · 18

T

Timer · 16

V

Version Control · 12